The utility of Sentinel-2 Vegetation Indices (VIs) and Sentinel-1 Synthetic Aperture Radar (SAR) for invasive alien species detection and mapping

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Abstract

The threat of invasive alien plant species is progressively becoming a serious global concern. Alien plant invasions adversely affect both ecological services and socio-economic systems. Hence, accurate detection and mapping of invasive alien species is valuable in mitigating adverse ecological and socio-economic effects. Recent advances in active and passive remote sensing technology have created new and cost-effective opportunities for the application of remote sensing to invasive species mapping. In this study, new generation Sentinel-2 (S2) optical imagery was compared to S2 derived Vegetation Indices (VIs) and S2 VIs fused with Sentinel-1 (S1) Synthetic Aperture Radar (SAR) imagery for detecting and mapping the American Bramble (Rubus cuneifolius). Fusion of S2 VIs and S1 SAR imagery was conducted at pixel level and multi-class Support Vector Machine (SVM) image classification was used to determine the dominant land use land cover classes. Results indicated that S2 derived VIs were the most accurate (80%) in detecting and mapping Bramble, while fused S2 VIs and S1 SAR were the least accurate (54%). Findings from this study suggest that the application of S2 VIs is more suitable for Bramble detection and mapping than the fused S2 VIs and S1 SAR. The superior performance of S2 VIs highlights the value of the new generation S2 VIs for invasive alien species detection and mapping. Furthermore, this study recommends the use of freely available new generation satellite imagery for cost effective and timeous mapping of Bramble from surrounding native vegetation and other land use land cover types.
Keywords
Alien species invasions, Sentinel-1, Synthetic Aperture Radar (SAR), Sentinel-2, Vegetation Indices (VIs), American Bramble, Fusion, Support Vector Machine (SVM)

Introduction
Global biodiversity is increasingly becoming susceptible to pressure from invasive species (Butchart et al. 2010). Specifically, the rapid spread of invasive alien plants in several regions of the world has adversely impacted ecosystem health, native species diversity and local and national economies (Pysek et al. 2012; Schirmel et al. 2016; Convention on Biological Diversity 2009). Brooks et al (2006) highlight the imperative need for the protection of native biodiversity, a need further emphasised by the United Nations (UN) that declared the period between 2010 and 2020 as the decade of biodiversity (UNEP 2010). Moreover, increased costs associated with invasive alien species eradication and management programmes puts further pressure on biodiversity (Marbuah et al. 2014). The severity of the problem has increased the impetus on development of efficient and cost-effective approaches for the control and management of invasive alien plant species.

In South Africa, approximately two million hectares of land have been invaded by invasive alien plant species (van Wilgen et al. 2012). The south western, southern and eastern coastal and interior regions have been identified as highly vulnerable to invasion (Kotzé et al. 2010; van Wilgen et al. 2012; Clusella-Trullas and Garcia 2017). In KwaZulu-Natal (KZN) province, for instance, Erasmus (1984) notes that the cool and moist conditions favour a range of invasive alien plant species. The American Bramble (*Rubus cuneifolius*) has particularly thrived in the province’s western mountain ranges (Henderson 2011). Originating from North America, Bramble belongs to the *Rosaceae* family and has adverse direct and indirect impacts on biodiversity that include changes in nutrient cycling, increase in soil erosion, reduction in rangeland carrying capacity and viability, as well as effects on natural plant succession, fire patterns and behaviour and hydrological processes (Henderson 2001).

To develop optimal mitigation of spread and eradication approaches, determination of spatial cover and extent of Bramble infestation is paramount. Traditionally, surveys have been adopted for mapping and monitoring of invasive alien plant species (Tan et al. 2012; Shah and Reshi 2014). However, reliance on field-based surveys is often restrictive, as they are commonly time consuming, labour and resource intensive and unsuitable in inaccessible sites. Hence, the adoption of remotely sensed imagery for invasive alien species detection and mapping has recently gained popularity. Huang and Asner (2009) attribute this increase to improved sensor technology, facilitating detailed and large scale landscape mapping and monitoring. In the recent past, the majority of invasive alien plant species detection and mapping applications have relied on remotely sensed image spatial and spectral characteristics (Mirik et al. 2013; Müllerová et al. 2013). Other studies have proposed object-based textural and contextual characteristics (Zhou et al. 2008) and landscape thermal characteristics (Eisavi et al. 2008).
2015). However, the advent of new sensors with radar scanning capabilities provides new opportunities for invasive plant species detection and mapping (Bradley 2014). For instance, radar’s ability to determine surface structure and roughness, dielectric constant (moisture content) and slope angle and orientation offer great opportunities for invasive species mapping. The European Space Agency’s (ESA) sentinel constellation is a recent satellite that consists of the Sentinel-1 (S1) and Sentinel-2 (S2) earth observation instruments. Both sensors disseminate freely available multispectral optical (S2) and multi-polarised SAR (S1) data. The unique S1 and S2 sensor characteristics, such as large swath widths, medium to fine scale spatial resolutions, short re-visit times and additional bands (Frampton et al. 2013; Sentinel-1 User Handbook 2012) provide numerous opportunities to evaluate the potential of the sensors to improve the reliability of remote sensing approaches for invasive alien plant species mapping.

Conventional remote sensing of invasive alien species utilises spectral wavelengths of absorbed and reflected light by distinguishing certain pigments in leaves and inflorescence (Huang and Asner 2009; Mirik et al. 2013; Weisberg et al. 2017; Müllerová et al. 2013; Bradley 2014). Hence, the potential of S2 to detect and map invasive alien species exists (Rajah et al. 2018). Specifically, the sensor’s improved spectral resolution can be used to derive numerous band ratios and indices, useful for vegetation mapping. For example, spectral vegetation indices (VIs), derived from remotely sensed data, have become valuable in mapping and monitoring vegetation species (Jamali et al. 2014; Zhang et al. 2015; Orhan et al. 2014). VIs have several advantages over stand-alone spectral bands that include reduced effect of atmospheric conditions, canopy geometry and shading, decreased effect of soil background on canopy reflectance and enhanced variability of spectral reflectance of target vegetation (Liu et al. 2004; Viña et al. 2011). On the other hand, the unique characteristics of S1 SAR imagery could provide additional variables that could improve invasive alien species detection and mapping. SAR data can operate at wavelengths irrespective of cloud conditions or lack of illumination and is capable of acquiring data during day and night (Sentinel-1 User Handbook 2012). SAR offers detailed information on the often difficult to detect characteristics of vegetation such as shape, moisture and roughness (Chen et al. 2010). However, despite this potential, previous adoption of SAR imagery for invasive alien plant species mapping has been limited by high acquisition cost, limited area coverage and complex data pre-processing (McNairn et al. 2009). Hence, the provision of freely available SAR imagery from the S1 satellite provides new prospects for advancing the mapping and detection of invasive alien plant species.

Asner et al. (2008) and Zhang (2010) note that the fusion of imagery from various sensors, while applying appropriate methodologies, may be valuable for invasive alien species detection and mapping. Furthermore, conventional optical imagery and SAR are commonly believed to be complimentary (Zhu et al. 2012). Considering the above-mentioned advantages, as well as S2’s improved spatial, spectral and temporal characteristics valuable for generating VIs, the fusion of these datasets provides a unique opportunity to investigate the value of new generation sensors such as S1 and S2 in mapping alien species. Accordingly, this study sought to determine the perfor-
mance of conventional stand-alone S2 optical imagery, stand-alone S2 derived VIs and fused S2 VIs with S1 Synthetic Aperture Radar (SAR) imagery in detecting and mapping the American Bramble.

**Methodology**

**Study site**

This study was conducted at the uKhahlamba Drakensberg Park (UDP), a UNESCO proclaimed world heritage and nature conservation area. The area is situated along the western edge of the KwaZulu-Natal province of South Africa (Figure 1). The area experiences wet and humid conditions during summer (November to March) (Nel 2009), with rainfall ranging from 990–1130 mm (Dollar and Goudy 1999). Winters (May to August) are dry and cold, with common occurrence of snow and frost (Mansour et al. 2012). Mean annual temperatures average 16° C and annual rainfall averages 1000 mm and 1800 mm at lower and higher elevations, respectively (Tyson et al. 1976). The landscape is predominantly natural grassland with wiregrass – *Aristida purpurea*, weeping lovegrass – *Eragrostis curvula* and the common thatch grass – *Hyparrhenia hirta* as dominant species. According to Everson and Everson (2016), the UDP is one of the most valuable remnant grassland in the country. The area is also characterised by patches of natural shrubs (*Erica* spp.) and isolated dense groups of bushes and trees. In the recent past, Bramble has emerged within the UDP and has invaded significant portions of the landscape (Bromilow 2010).

**Field data collection**

Field data collection was conducted during spring and summer of 2016. A purposive sampling technique was utilised to record ground truth points of four major land cover classes (Bare rock, Bramble, Forest and Grassland). These seasons were chosen for field data collection as Bramble patches are most phenologically discernible from native vegetation. Ground control points were recorded as close to the centroid of Bramble patches as possible. Collected Bramble patches ranged from 15 m × 15 m to 50 m × 50 m. Ground truth point data collected from Bramble patches were spatially independent from each other to compensate for the spatial resolution of the satellite imagery utilised. This ensured that each Bramble patch fell within a single image pixel and could be associated with the unique spectral reflectance of a specific pixel. Due to the area’s steep and mountainous terrain, hence restricted accessibility, only Bramble patches that could be accessed by foot were considered for this study. In addition, aerial photographs at a 0.5 m spatial resolution captured in 2016 were used to supplement and verify selected land cover ground truth points. In total, 15, 40, 45 and 60 ground truth points were used for Bare rock, Forest, Grassland and Bramble, respectively.
Image acquisition

Optical Imagery

The Sen2Cor plugin ESA SNAP toolbox 3.0 (European Space Agency 2018) was used to convert summer Sentinel-2 level-1C raw products to surface reflectance values in the Sen2Cor plugin. Images were corrected for topographic effects to remove shadows associated with mountainous areas using the System for Automated Geoscientific Analyses SAGA (2.1.2) terrain analysis lighting tool within the Quantum GIS (QGIS) environment on a band by band basis (Conrad et al. 2015). The correction of topographic effects is a tool within the SAGA software that best adjusts optical imagery for topographic effects of shadow (Conrad et al. 2015).

Sentinel-1 Synthetic Aperture Radar (SAR) Imagery

Summer Synthetic Aperture Radar (SAR) data were downloaded from the Sentinel-1 data hub. Sentinel-1 level-1 Ground Range Detected (GRD) products were multi-looked and projected to ground range using an earth ellipsoid model. SAR Vertical-Horizontal (VH) polarised imagery was acquired using the Interferometric Wide Swath (IW) mode, with a spatial resolution of 20 metres and a 250 km² swath width. Pre-processing of SAR imagery was conducted using the ESA SNAP toolbox following the methodology outlined in Bevington (2016). The Bevington (2016) SAR image processing chain consists of 5 steps: (1) Application of orbit file to SAR image; (2) Radiometric calibration; (3) Terrain correction; (4) Application of speckle filter; (5)
Convert SAR DN to Gamma backscatter values. Polarisation of SAR imagery recorded in Vertical Horizontal (VH) acquisition mode was fused with S2 derived VIs. SAR backscatter measurements are believed to be a function of polarisation and target object characteristics, such as geometry, roughness and dielectric properties (Vyjayanthia and Nizalapur 2010).

**Sentinel-2 derived Vegetation Indices (VIs)**

Sixty-five Vegetation Indices (VIs), selected from the online Index Database (IDB) (www.indexdatabase.de), were calculated from summer Sentinel-2 surface reflectance optical imagery. The IDB is a tool developed to provide a simple overview of satellite specific vegetation indices that are usable from a specific sensor for a specific application (Henrich et al. 2009). All VIs were calculated within a python 2.7.13 environment using listed formulae from the IDB and spectral reflectance Sentinel-2 bands (Table 1). The 10 most influential VIs were selected for stand-alone classification results and subsequent image fusion with SAR imagery in order to produce a fused VIs and SAR classification result. The top 10 VI selections were determined using the Variable Importance in the Projection (VIP) method. Variable Importance in the Projection aims to improve classification accuracy by recognising a subset of all initial variables (VIs) that, if combined, could increase classification accuracies with parsimonious representation (Farrés et al. 2015; Xu et al. 2018). As aforementioned, the study area is predominantly natural grassland, regarded as a valuable economic and environmental resource. Hence, in addition to Bramble, it was necessary to reliably determine the spatial extent of grassland. In this regard, the VIP was used to determine the importance of each VI in increasing the two land use land cover’s user’s and producer’s accuracies.

<table>
<thead>
<tr>
<th>VIP Vegetation Indices (VIs)</th>
<th>VI formula (S2 optical bands)</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Datt2 (Simple Ratio 850/710)</td>
<td>Near Infrared (NIR)/Red Edge 1</td>
<td>Datt 1999</td>
</tr>
<tr>
<td>PSSRc2 (Simple Ratio 800/470 Pigment specific simple ratio C2)</td>
<td>Near Infrared (NIR)/Blue</td>
<td>Blackburn 1998</td>
</tr>
<tr>
<td>RDVI (Renormalized Difference Vegetation Index)</td>
<td>Near Infrared - Red/(Near Infrared + Red)^(0.5)</td>
<td>Roujean and Breon 1995</td>
</tr>
<tr>
<td>SR520/670 (Simple Ratio 520/670)</td>
<td>Blue/Red</td>
<td>Henrich et al. 2009</td>
</tr>
<tr>
<td>SR833/1649 (Simple Ratio 833/1649 MSIhyper)</td>
<td>Near Infrared /Shortwave Infrared1</td>
<td>Henrich et al. 2009</td>
</tr>
<tr>
<td>SRRMIR/Red (Simple Ratio MIR/Red Eisenhydroxid-Index)</td>
<td>Shortwave Infrared2/Red Edge 1</td>
<td>Henrich et al. 2009</td>
</tr>
<tr>
<td>TM5/TM7 (Simple Ratio 1650/2218)</td>
<td>Shortwave Infrared1/ Shortwave Infrared2</td>
<td>Henrich et al. 2009</td>
</tr>
</tbody>
</table>
Image fusion

Pixel level image fusion, based on ground truth points, was used to merge the ten most influential VIP VIs and Sentinel-1 SAR imagery (a description of image fusion levels can be found in Hong et al. (2014). All VIs were derived from S2 optical bands, at a spatial resolution of 20 m. Extraction of feature pixels (ground truth points) were done separately for optical imagery (spectral reflectance measurements) and SAR imagery (backscatter measurements). Corresponding backscatter measurements were then assigned to the corresponding extracted spectral reflectance of ground truth points. Optical and SAR imagery were then fused using the composite band tool in ArcMap 10.4. This was achieved by stacking optical and SAR imagery on a band by band basis, creating a composite (fused) image containing both spectral reflectance and backscatter measurements at respective ground truth points. The fused image was then used for image analysis.

Image classification

Image classification was conducted post pixel level image fusion as outlined in Pandit and Bhiwani (2015). The Support Vector Machine (SVM) algorithm was run using the scikit-learn package in a Python environment. The SVM algorithm is a supervised statistical learning technique initially developed to handle binary classification (Vapnik 1979). SVM aims to identify a hyper-plane that is able to distinguish the input dataset into a predefined discrete number of classes consistent with training data (Mountrakis and Ogole 2011). Several evaluations of SVM have shown that the algorithm is capable of delineating several classes with a small number of support vectors as training data, without ultimately compromising classification accuracies (Foody and Mathur 2004; Mantero et al. 2005; Bruzzone et al. 2006; Shao and Lunetta 2012; Zheng et al. 2015). Spectra were extracted using ground truth points of the aforementioned major land cover classes. The fused VIP vegetation indices and SAR image measurements were used to define the SVM feature space and a radial basis kernel function used to determine optimal hyperplanes that differentiate the different land cover classes. Waske et al. (2010), for instance, established that the approach is superior to the polynomial function. Furthermore, this approach is known to be fast and computationally efficient, with a two parameter tuning requirement; cost ‘sigma (C)’ for error adjustment of misclassified instants of training data and kernel width ‘gamma (γ)’ (Waske et al. 2010). As recommended by Hsu and Lin (2002), the one-against-one approach was used to implement a multiclass-based SVM model.

Spatial cover map production and validation

Support Vector Machine classification maps were generated for S2 optical imagery, Vegetation Indices and for the fused VIS and SAR imagery within a Python environ-
ment. Training data (70%) of all four considered land cover classes were used as the input for Bramble spatial cover maps. The respective test dataset (30%) was then used to assess classification accuracies across all imagery. A confusion matrix was generated from the SVM process and user and producer accuracies used to quantify the reliability of the resultant Bramble spatial cover maps. In a confusion matrix, the overall accuracy is determined by dividing correctly classified pixels by the total number of pixels checked (Congalton and Green 1999). Two other measures, producer’s and user’s accuracy, can also be generated from the matrix. Producer’s accuracy is determined by dividing the total number of correct pixels in one class divided by the total number of pixels as derived from reference data (Congalton and Green 1999). It is a measure of how well an area has been classified and is expressed as:

\[
\text{Producer’s accuracy (\%) } = 100\% - \text{error of omission (\%)}
\]  

(1)

User’s accuracy on the other hand is a measure of map reliability and provides information on how well a map represents ground features. It is expressed as:

\[
\text{User’s accuracy (\%) } = 100\% - \text{error of commission (\%)}
\]  

(2)

Results

Sentinel-2 optical bands

The overall classification accuracy using S2 optical bands was 78\% (Table 2). Bramble produced the lowest users’ accuracy (46\%) across all considered classes, while Grassland produced the lowest producers’ accuracy (69\%) (Table 3). Results produced using only S2 optical bands were used as a benchmark for classification using VIs and VIs fused with SAR imagery.

A large overestimation of Bramble discrimination and spatial cover using S2 optical bands was evident (Figures 2b and 3a). An underestimation in Grassland discrimination and spatial cover was observed, as the SVM algorithm could not effectively distinguish between Bramble and Grassland (Table 3, Figure 2b). An underestimation in the spatial cover of the Bare rock class was also evident, as there was consistent misclassification of Bare rock from Grassland and Bramble (Figures 2b and 3a).

Vegetation Indices (VIs)

Discrimination and mapping of Bramble using vegetation indices produced the highest overall accuracy (82\%) when compared to the benchmark of using only S2 optical image bands (Table 3). A users’ accuracy of 72\% for Bramble surpassed those achieved by S2 optical imagery as well as fused vegetation indices and SAR imagery (Table 1).
The utility of Sentinel-2 Vegetation Indices (VIs) and Sentinel-1 Synthetic Aperture Radar ...

Table 2. Support Vector Machine (SVM) confusion matrix using Vegetation Indices for Bramble mapping and discrimination. Where BR = Bare rock; BBL = Bramble; FR = Forest; and GR = Grassland, UA = Users accuracy; PA = Producers accuracy and OA = Overall accuracy.

<table>
<thead>
<tr>
<th>S2 (Optical bands)</th>
<th>BR</th>
<th>BBL</th>
<th>FR</th>
<th>GR</th>
<th>UA (%)</th>
</tr>
</thead>
<tbody>
<tr>
<td>BR</td>
<td>33</td>
<td>2</td>
<td>0</td>
<td>11</td>
<td>70</td>
</tr>
<tr>
<td>BBL</td>
<td>0</td>
<td>24</td>
<td>0</td>
<td>30</td>
<td>46</td>
</tr>
<tr>
<td>FR</td>
<td>1</td>
<td>1</td>
<td>51</td>
<td>3</td>
<td>92</td>
</tr>
<tr>
<td>GR</td>
<td>2</td>
<td>3</td>
<td>7</td>
<td>94</td>
<td>89</td>
</tr>
<tr>
<td>PA (%)</td>
<td>92</td>
<td>81</td>
<td>87</td>
<td>69</td>
<td></td>
</tr>
<tr>
<td>OA (%)</td>
<td>78</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Table 3. Support Vector Machine (SVM) confusion matrix using Sentinel-2 optical bands for Bramble mapping and discrimination. Where BR = Bare rock; BBL = Bramble; FR = Forest; and GR = Grassland, UA = Users accuracy; PA = Producers accuracy and OA = Overall accuracy.

<table>
<thead>
<tr>
<th>Vegetation Indices (VIs)</th>
<th>BR</th>
<th>BBL</th>
<th>FR</th>
<th>GR</th>
<th>UA (%)</th>
</tr>
</thead>
<tbody>
<tr>
<td>BR</td>
<td>51</td>
<td>11</td>
<td>0</td>
<td>0</td>
<td>83</td>
</tr>
<tr>
<td>BBL</td>
<td>0</td>
<td>53</td>
<td>19</td>
<td>4</td>
<td>72</td>
</tr>
<tr>
<td>FR</td>
<td>1</td>
<td>0</td>
<td>54</td>
<td>0</td>
<td>97</td>
</tr>
<tr>
<td>GR</td>
<td>13</td>
<td>7</td>
<td>0</td>
<td>57</td>
<td>74</td>
</tr>
<tr>
<td>PA (%)</td>
<td>83</td>
<td>78</td>
<td>76</td>
<td>91</td>
<td></td>
</tr>
<tr>
<td>OA (%)</td>
<td>84</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Figure 2. Support Vector Machine (SVM) classification maps produced utilising (a) Vegetation Indices; (b) S2 optical bands and (c) Fused VIs and SAR.

The classification map resulting from fused vegetation indices and SAR imagery showed the most accurate discrimination and spatial cover of all considered land cover classes. The Grassland and Bare rock classes were reliably discriminated (Figures 2a
and 3b). In addition, the spatial discrimination and cover of Bramble was reliably discriminated as compared to the S2 optical band benchmark and the fused VIs and SAR imagery (Figures 2a and 3b).

**Vegetation Indices (VIs) and S1 SAR imagery**

The ten most influential S2 VIs were selected for pixel level image fusion with S1 SAR imagery. Using VIP, the influence of VIs was identified by the importance on increasing Grassland and Bramble’s User’s and Producer’s accuracy, hence, the ten bands that generated the ten highest classification accuracies were selected. Five of the selected VIs incorporated the Near Infrared (NIR) optical band, while three selected VIs were derived using Shortwave Infrared 1 (SWIR1) and Shortwave Infrared 2 (SWIR2) optical bands (Table 1). The SR520/670 and SR672/550 VIs were the only two VIP VIs derived using bands within the visible portion of the electromagnetic spectrum (Table 3).

The fusion of VIs and S1 SAR imagery produced the lowest overall accuracy (55%) when compared to the benchmark of S2 optical band results (Table 4). Bramble users’ and producers’ accuracies were 29% and 20%, respectively (Table 4), the lowest in all
classes. The Forest (73% and 100%) and Bare rock (79% and 97%) classes were the highest users’ and producers’ accuracies, respectively.

The SVM classification map, produced using fused vegetation indices and SAR, resulted in an underestimation of the Bramble class, while an overestimation of the Grassland class was observed (Figure 2c). Although the Forest class received high users’ and producers’ accuracies, the overall distribution and discrimination were overestimated when compared to the benchmark (Figures 2c and 3c).

**Discussion**

This study sought to determine the potential of derived Vegetation Indices (VIs) and fused VIs and Synthetic Aperture Radar (SAR) imagery to improve invasive alien species detection and mapping. The overall classification accuracy of optical imagery was used as the benchmark for comparison of the results achieved using S2 VIs and fused VIs and SAR. Opposing the expected outcome, fused VIs and SAR imagery produced the lowest classification accuracy (55%) compared to conventional S2 optical imagery (78%). Moreover, S2 derived VIs produced the highest classification accuracy (84%) when compared to conventional S2 optical imagery and fused VIs and SAR.

Poor performance of fused VIs and SAR imagery was unanticipated and opposes research done by Sano et al. (2005), who noted that the combination of VIs and SAR for discrimination within a savannah environment was complementary and improved overall discriminant analysis. Sano et al. (2005) also noted that VIs and SAR were able to easily separate Grassland from woodlands. However, Sano et al. (2005) also reported increased confusion between Grassland and shrub species when utilising fused VIs and SAR. This provides some indication that previous studies have also encountered unanticipated results when combining VIs and SAR for discrimination purposes. Poor overall classification accuracies of fused VIs and SAR imagery can further be attributed to vegetation structure and roughness, as this plays a major role in measured SAR backscatter values. Similar difficulties were documented by Millard and Richardson (2018) who note that, even though it is well established that vegetation roughness influences

<table>
<thead>
<tr>
<th>VIs and SAR</th>
<th>BR</th>
<th>BBL</th>
<th>FR</th>
<th>GR</th>
<th>UA (%)</th>
</tr>
</thead>
<tbody>
<tr>
<td>BR</td>
<td>43</td>
<td>2</td>
<td>0</td>
<td>11</td>
<td>79</td>
</tr>
<tr>
<td>BBL</td>
<td>0</td>
<td>15</td>
<td>0</td>
<td>38</td>
<td>29</td>
</tr>
<tr>
<td>FR</td>
<td>1</td>
<td>0</td>
<td>45</td>
<td>17</td>
<td>73</td>
</tr>
<tr>
<td>GR</td>
<td>0</td>
<td>53</td>
<td>0</td>
<td>39</td>
<td>42</td>
</tr>
<tr>
<td>PA (%)</td>
<td>97</td>
<td>20</td>
<td>100</td>
<td>37</td>
<td></td>
</tr>
<tr>
<td>OA (%)</td>
<td>55</td>
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</table>
SAR backscatter, characterising these variables spatially and temporally within natural environments remains a challenge. Although results from fused VIs and SAR were unexpected, similar poor performance using the same combination of variables is not unprecedented. For example, Torma et al. (2004) also experienced poor performance when fusing VIs and SAR.

Patel et al. (2006) and Srivastava et al. (2009) note that the magnitude of SAR backscatter is dependent on SAR band frequency, for instance, SAR backscatter signatures at high frequency (e.g. X-band SAR) are known to be sensitive to subtle variations in vegetation phenology attributed to deep canopy penetration. Sentinel-1 C-band SAR is considered low frequency (decreased canopy penetration) SAR imagery and could have experienced difficulty in discerning between Bramble characteristics and surrounding native vegetation when using fused VIs and S1 SAR imagery (Khosravi et al. 2017; Duguay et al. 2015; Naidoo et al. 2015; Hajj et al. 2014; van Beijma et al. 2014; Turkar et al. 2012). The influence of sensor incident angle on SAR backscatter is known to be interpreted using the same mechanism, particularly for lower frequencies of SAR. Inoue et al. (2002) notes that correlations to plant physiological characteristics, such as Leaf Area Index (LAI), canopy height and stem density, decrease with an increasing incident angle. This is mainly attributed to the penetration of SAR microwaves responsible for backscatter measurements, as smaller incident angles are able to penetrate deeper into canopy cover, hence extract more physiological information (McNairn et al. 2009). The relatively large incident angle of S1 (46°) (Sentinel-1 User Handbook 2012) could have hindered its ability to distinguish vegetation physiological information, which could serve to justify decreased classification accuracies achieved using fused VIs and SAR imagery (de Almeida Furtado et al. 2016; Naidoo et al. 2015; Frampton et al. 2013; Vyjayanthia and Nizalapur 2010). The influence of soil moisture and roughness on leaf and stalk SAR backscatter measurements is considered a weakness of SAR imagery across specific classification applications (Moran et al. 2002). SAR imagery could have served to increase confusion between Bramble and surrounding native vegetation when fused with S2 VIs.

The use of S2 VIs outperformed the benchmark accuracy achieved by conventional S2 optical imagery. Similar results were achieved by Kandwal et al. (2009), where selected VIs performed well in discriminating Lantana camara (Verbenaceae), an invasive alien plant with similar growth pattern and phenology to Bramble. The majority of VIs, selected as VIP indices, were dominated by VIs incorporating the Near Infrared (NIR), Shortwave Infrared (SWIR) and red edge S2 bands. A study by Zhao et al. (2007) produced similar results, where VIs, derived from SWIR, red-edge and NIR bands, were reported to be closely correlated to canopy LAI and canopy chlorophyll density. Chuai et al. (2013), for instance, used NDVI to determine seasonal vegetation correlations with lag-time climatic effects in Inner Mongolia between 1998 and 2007. They established varied seasonal changes and concluded that NDVI provides a reliable measure of vegetation changes attributed to climatic variability. According to Domaç et al. (2004), VIs can extract valuable information by generating a new variable set without inter-band correlation and reduced data dimensionality. Whereas the NDVI
The utility of Sentinel-2 Vegetation Indices (VIs) and Sentinel-1 Synthetic Aperture Radar ... has commonly been preferred in vegetation mapping, El-Mezouar et al. (2010) suggests that Soil Adjusted Vegetation Index (SAVI) is more suitable for mapping patchy vegetation characterised by lower percentage cover. A recent study by Tarantino et al. (2019) in Apulia region, southern Italy, concluded that indices like MSAVI on World-View2 imagery are effective in discriminating the invasive *Ailanthus aitissina* species. This superior performance is attributed to the indices’ maximal reduction of background soil effect on vegetation reflectance (Qi et al. 1994). Other studies like Große-Stoltenberg et al. (2018) used 15 vegetation indices to determine an *Acacia lonifolia* cove in a dune ecosystem and concluded that the fusion of vegetation indices with LiDAR could effectively determine the effects of species invasion on the dune landscape.

Eight of the ten VIP VIs selected for Bramble discrimination and mapping were derived from at least one of these three spectral bands. The strong relationship between NIR, SWIR and red edge bands to variable vegetation parameters could have resulted in the increased accuracy of Bramble discrimination and mapping. Moreover, reflectance within the visible region of the spectrum is largely determined by vegetation pigments and is commonly used to quantify vegetation physiological properties (Li et al. 2013; Zhao et al. 2007). The collective capability of combined VIs to discriminate various vegetation parameters could further explain the increased overall classification accuracy achieved using stand-alone vegetation indices.

Several studies (e.g. Royimani et al (in press) – *Perthenium*, Matongera et al. (2017) - *Pteridium aquilinum* (L.) Kuhn, Robinson et al. (2016) - *Mesquite* (prosopis spp.), Peters et al. (1992) - *Gutierrezia sarothrae* and Oumar (2016) - *Lantana camara* have discriminated invasive species from native vegetation using spectral variability. Matongera et al. (2017) and Zhao et al. (2009) attribute this to invasive species’ dissimilar biophysical (e.g. texture, canopy, leaf structure and orientation) and biochemical (e.g. chlorophyll and water content) characteristics from the surrounding vegetation species. According to Blossey and Notzold (1995), invasive species are commonly characterised by superior physical development due to disproportionate availability or exploitation of resources. Such differences, particularly volume and height, facilitate their discrimination. Goodwin et al. (1999), for instance, noted that differences in stem heights and flowering periods could be used to discriminate invasive species from native vegetation, while Peerbhay et al. (2016) found that dense infestation, particularly in new habitats, facilitate discrimination. Commonly, the phenology of invasive species differs from native plants. Holland and Aplin (2013) and Page (2010) note that the discreet reflectance of invasive species at different seasons offers great potential for their discrimination. This is consistent with Santos and Ustin (2018) who noted that fennel (*Foeniculum vulgare*) could be effectively discriminated by considering seasonal foliar variability from surrounding grasses. In this study, Bramble’s broad leaves could have facilitated its discrimination, a finding in agreement with Hong et al. (2014) who successfully discriminated alfalfa in the Prairie Provinces of Canada.

According to Motohka et al. (2010), the potential of green-red VIs for phenological vegetation discrimination exists. VIs derived from ratios of red and green optical bands are known to be sensitive to variations in canopy colour, where changes in
visible characteristics of vegetation canopy are often timeously detected (Motohka et al. 2010). The SR672/550 VI, an index derived solely from S2 red and green optical bands, suggests an agreement with Motohka et al. (2010). The SR672/550 VI could have assisted in the discrimination of Bramble as it produces noticeable white inflorescence during summer, a significant phenological trait that could have been exploited. This potential is further enhanced by S2’s higher temporal resolution (five days, with possible higher resolution due to overlap in swaths of adjacent orbits) that facilitates single scene’s image turnover. Although the combined potential of VIs and SAR imagery produced the lowest overall classification accuracy, the potential of the latest and advanced spectrally derived VIs was evident when compared to the benchmark set by conventional S2 optical imagery. While the fusion of S2 VIs and SAR showed limited utility with regard to accurately mapping Bramble, the complementarity of these datasets has previously been documented. Our findings are consistent with existing literature. For instance, in lower Magdalena region, Colombia, Clerici (2017) established that Sentinel 1 and 2 fused dataset, classified using SVM, generated the highest classification accuracy of the existing land use land covers. Hence, the study recommended the use of radar sensor due to its all-weather capability and the spectral wealth of the optical sensor. Niculescu et al. (2018) mapped major vegetation types by fusing S1, S2 and SPOT – 6 in Pays de Brest, France by stacking time series data using Random Forest supervised classification. The study achieved a 93% classification accuracy when the major vegetation indices (Normalised Difference Vegetation Index - NDVI, Normalised Difference Wetness Index NDWI, Inverted Red-Edge Chlorophyll Index – IRECI and Sentinel-2 Red-Edge Position - S2REP) were used in the classification process. The study recommends the use of S1 and S2 due to free availability and improved sensor capabilities.

**Conclusion**

This study utilised freely available advanced Sentinel-1 radar and Sentinel-2 optical imagery, with the aim of evaluating spectrally derived VIs and fusing Synthetic Aperture Radar (SAR) imagery for improving American Bramble (Rubus cuneifolius) detection and mapping. This study contributes to the evaluation of economically viable, efficient and large scale invasive alien species detection and mapping. Conventional S2 optical imagery was used as a benchmark for comparison with results achieved using S2 VIs and fused VIs and S1 SAR imagery. The use of S2 VIs increased overall classification accuracies when compared to traditional optical imagery results, while the fusion of S2 VIs and S1 SAR decreased the overall accuracies. Hence this study demonstrated that new generation S2 VIs have the potential to increase the detection and mapping of Bramble from surrounding native vegetation. Results further indicate that the fusion of VIs and SAR imagery for Bramble detection and mapping failed to increase overall classification accuracies, hence have limited utility when applied to Bramble detection and mapping. The new generation satellites, such as S1 and S2, possess unprecedented sensor characteristics like higher temporal and spatial
resolution, as well as tandem acquisition of SAR data, hence valuable for improved landscape mapping. This study concludes that the recently launched Sentinel satellite, with optical and radar capabilities, holds great promise in landscape delineation and vegetation mapping.

References


The utility of Sentinel-2 Vegetation Indices (VIs) and Sentinel-1 Synthetic Aperture Radar ...


